



targets



Common Digital Architecture

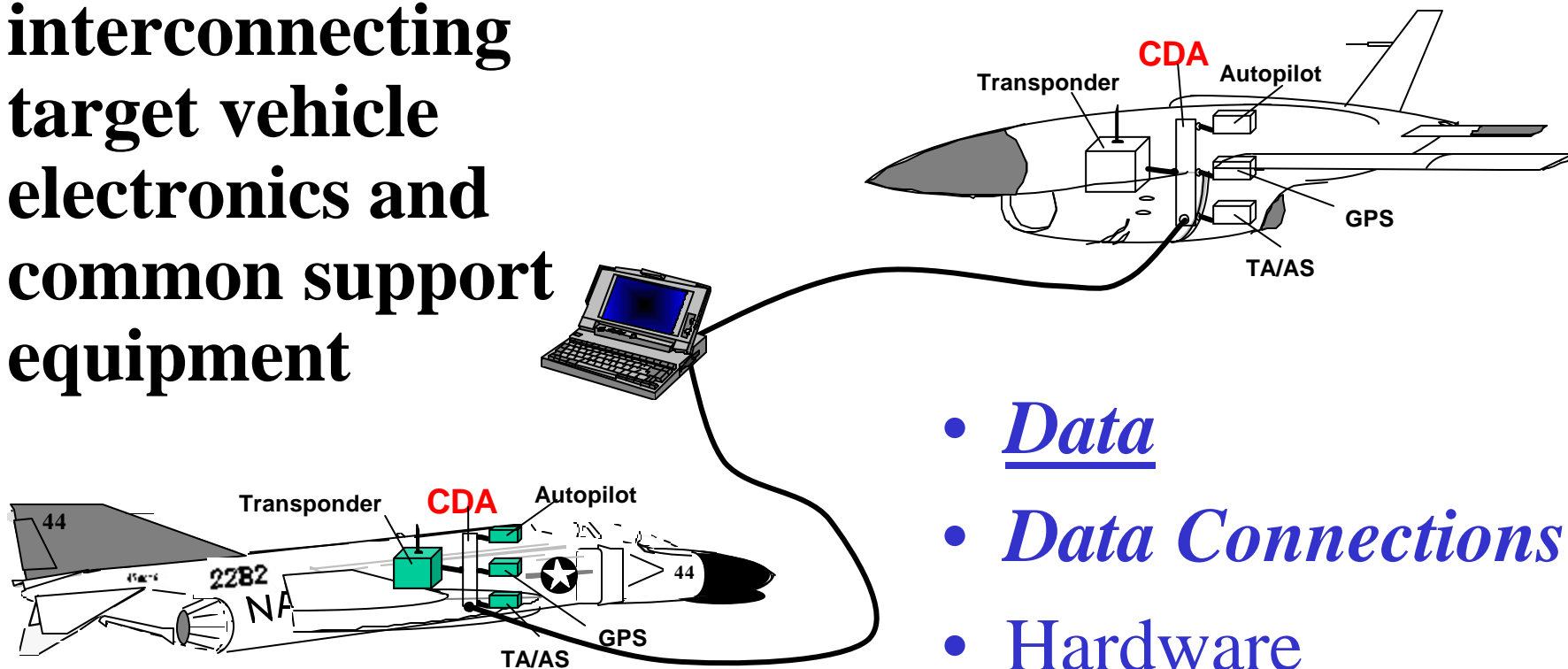
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Catch the Wave



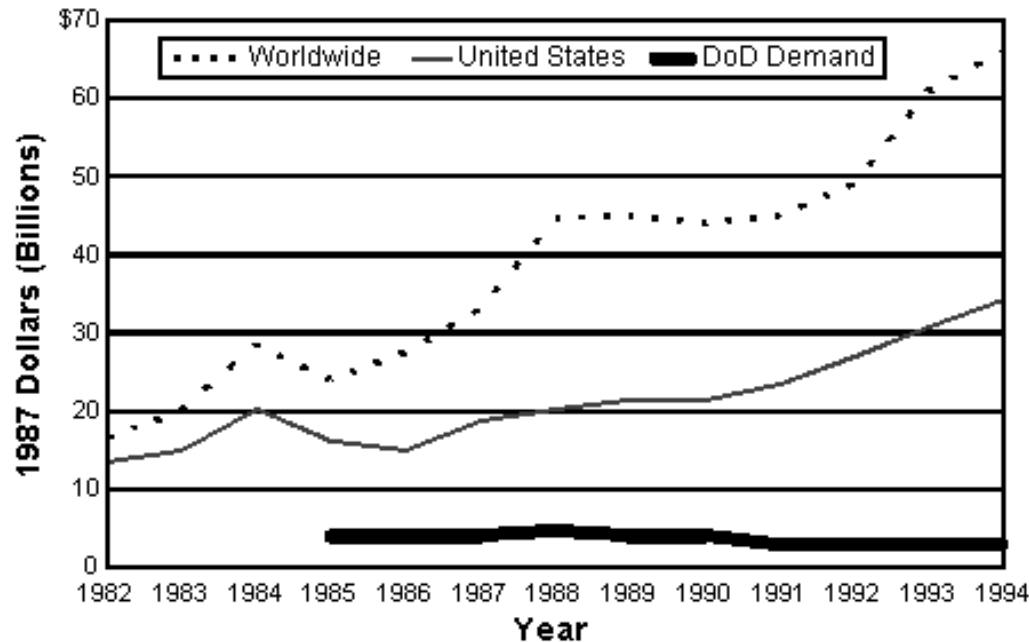
Standard for
interconnecting
target vehicle
electronics and
common support
equipment



- Data
- *Data Connections*
- Hardware



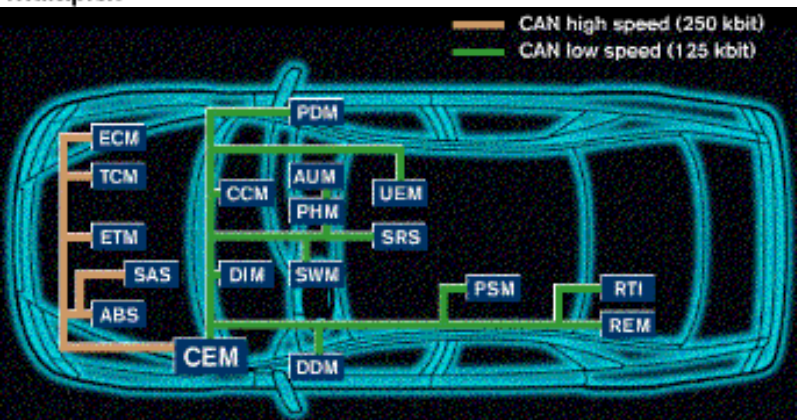
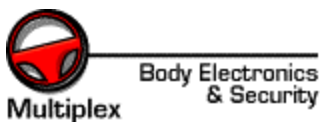
DoD no longer drives the market



Due to the changes within the defense market segment, as well as the required deployment within our business group, Intel has decided to End Life of their Military and Special Environment products.



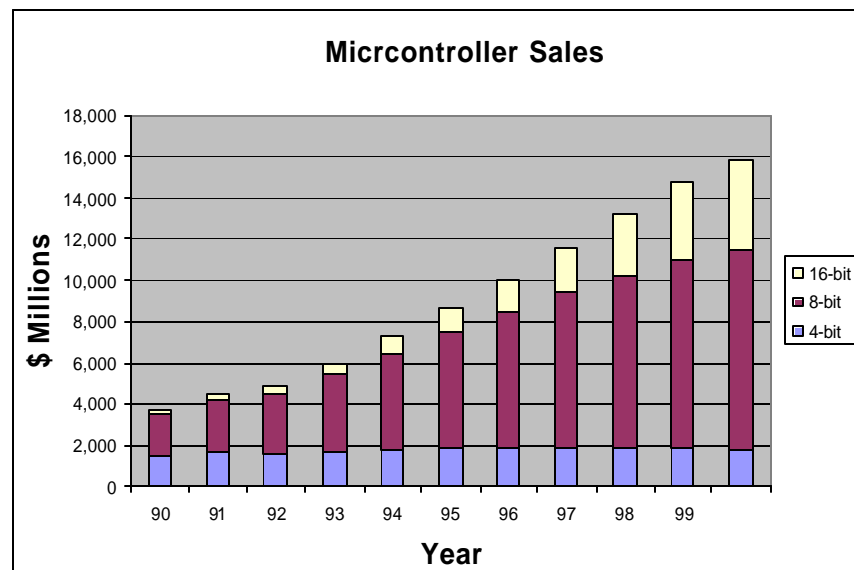
what's industry doing?



MUX uses one or more serial networks in order to achieve:

- Reduction of the number of wires within a vehicle
- Increased functionality
- Increased flexibility
- Virtual integration of system functions
- Improved systems diagnostics

- Microcontrollers are going into everything from washing machines to automobiles.
- The volume is driving cost down and capabilities up.
- Inexpensive 'smart' devices are a reality





early years



- **FY 97**
- Workshops
- CDA 101 standard
- Insertion Plan



- **FY 98**
- Seaborne Target Demonstration
- BQM-74 Implementation Report
- MQM-107 Implementation Report
- Gateway Design and AF Report



specification building blocks



Road vehicles -- Interchange of digital information -- Controller Area Network (CAN) for high-speed communication

International Organization for Standardization



NMEA 2000

STANDARD FOR SERIAL-DATA NETWORKING OF MARINE ELECTRONIC DEVICES



CAN KINGDOM

A set of protocol primitives, and a tool for a system designer to create an optimized higher layer protocol.

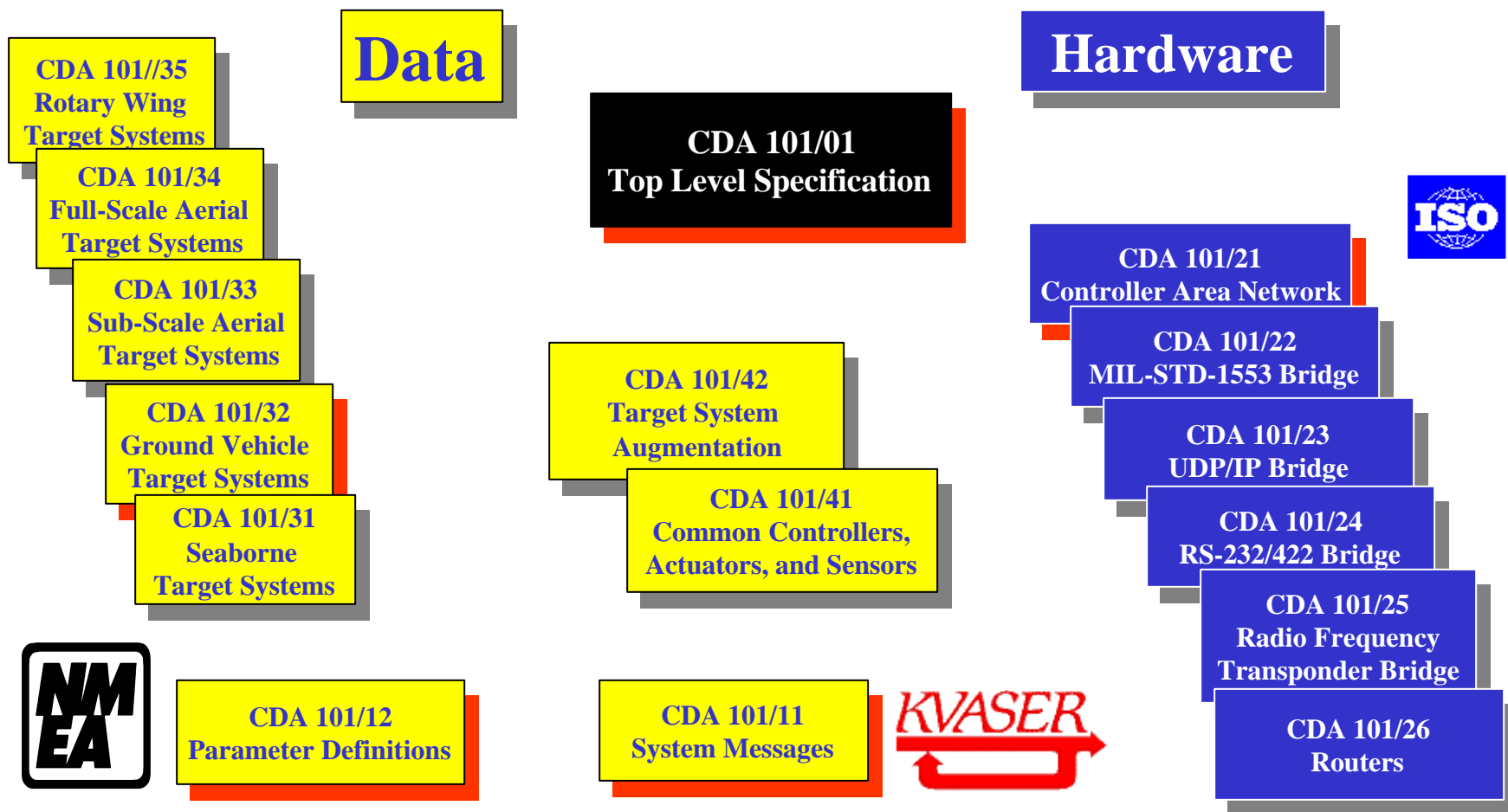


Target Unique Data Requirements



CDA 101

The Specification

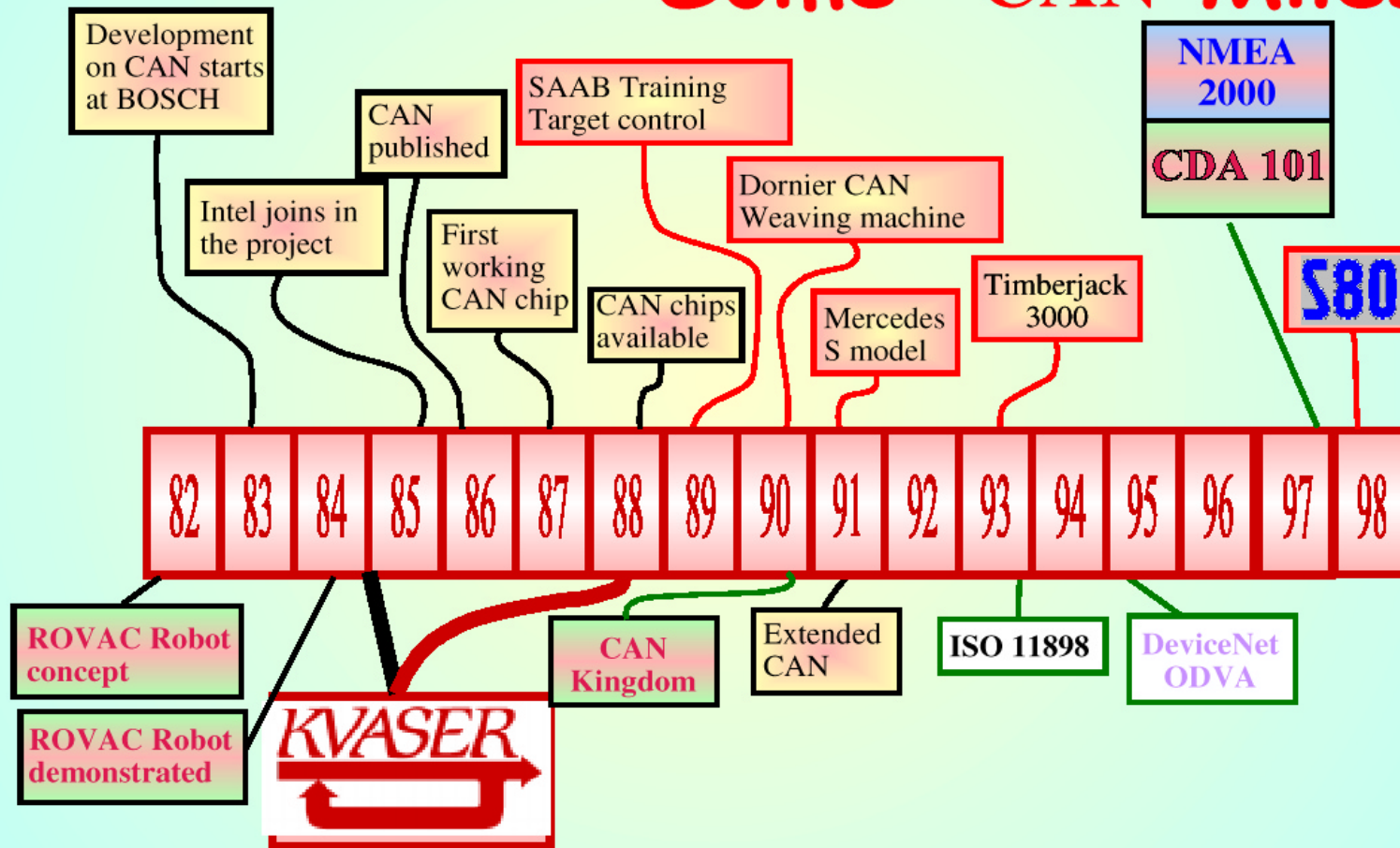




controller area network



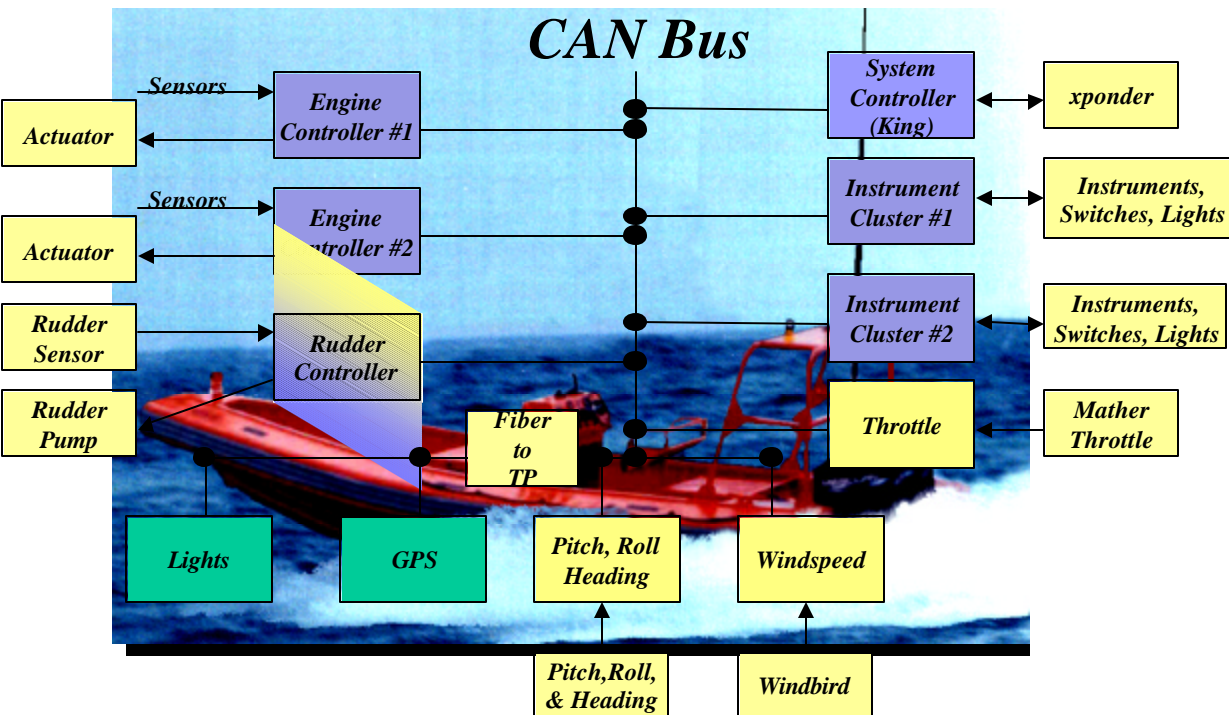
Some CAN Milestones





SI2000

Seaborne Target 2000



CDA 101 Hardware/Software Reference Design

- 25% reduction in electronics cost
- Marked increase in flexibility
- Simplified maintenance & logistics
- Reduction in development time



unclassified



FY99/01 program overview



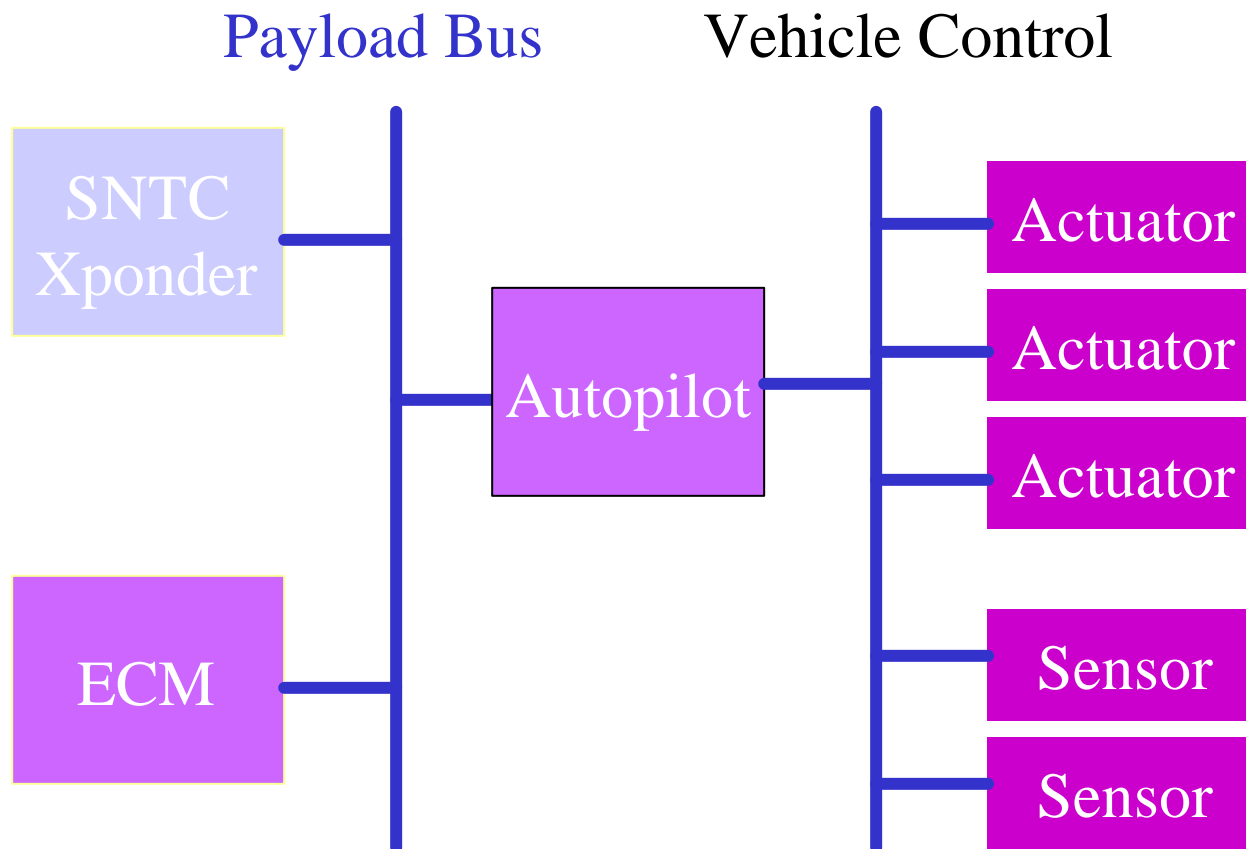
- Training
- BQM-74 Implementation
- MQM-107 Implementation
- ECM Implementation
- Ground Target System



- QF-4 Low Cost GPS Evaluation
- Compliance/Evaluation Procedure



notional target diagram





MQM-107



Payload Bus

Vehicle Control Bus



ECM

Xponder

Autopilot



Interface

Interface

Actuators

Interface

Sensors





integration into MQM-107



- FY99
 - Modified SPVI
 - Ground HIL
- FY00
 - Modify ground station
 - Flight nodes
- FY01
 - Flight Test



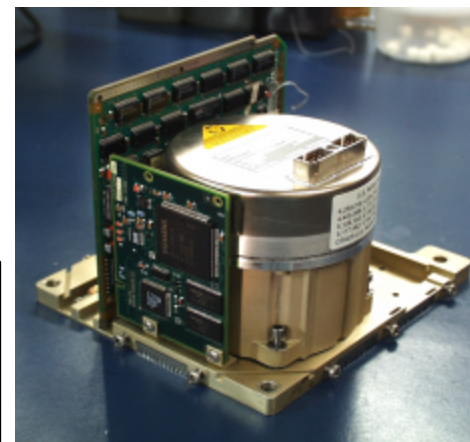
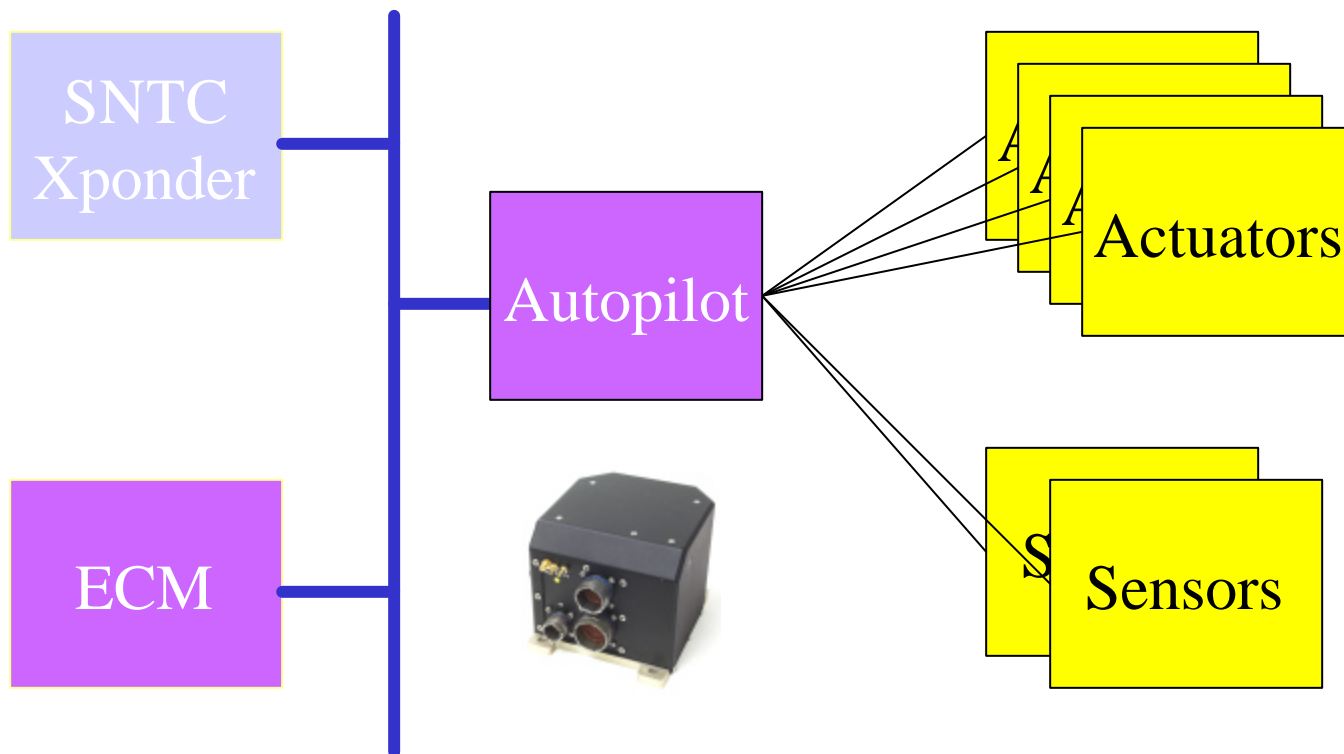


BQM-74



Payload Bus

Vehicle Control





integration into BQM-74

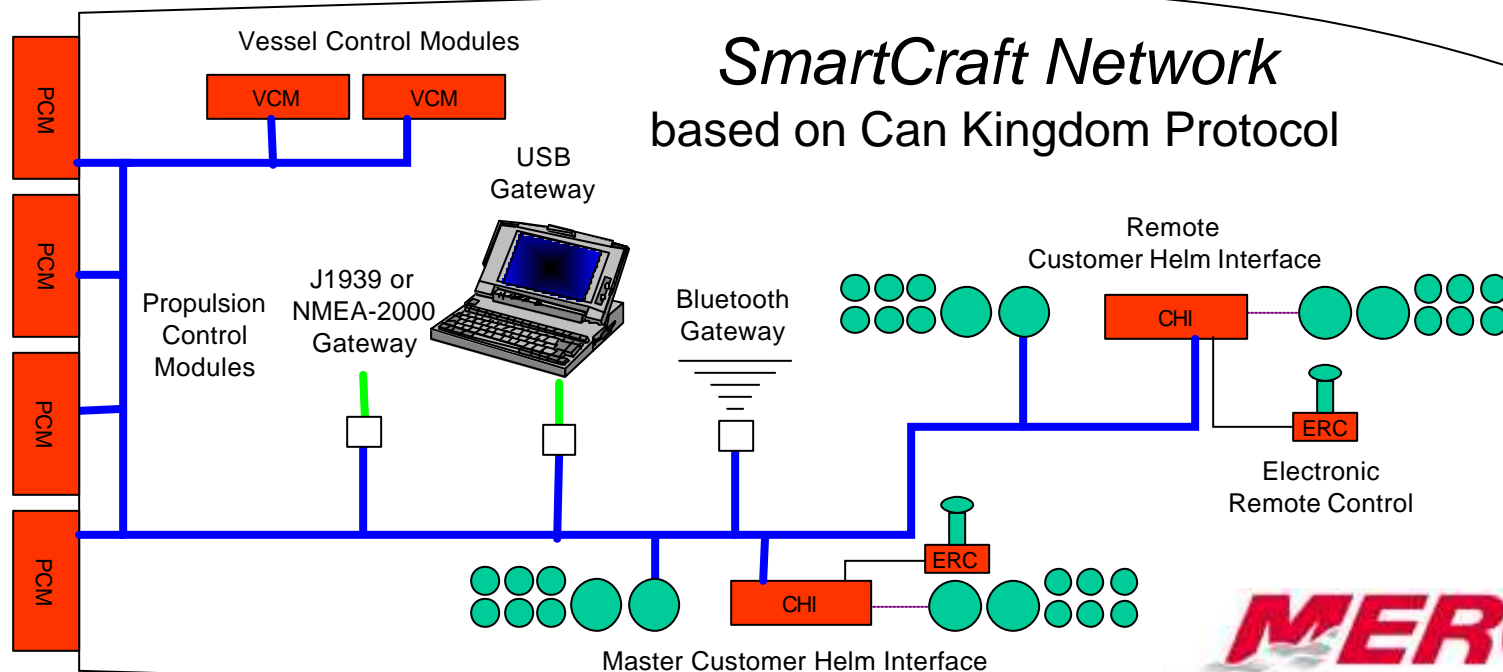


- FY99
 - Modified IAU
 - Modified ULQ-21
 - Ground Demonstration
- FY00
 - Modify SNTC transponder and ground station
- FY01
 - Ground Integration Demonstration





Mercury Marine SmartCraft



MERCURY
SmartCraft

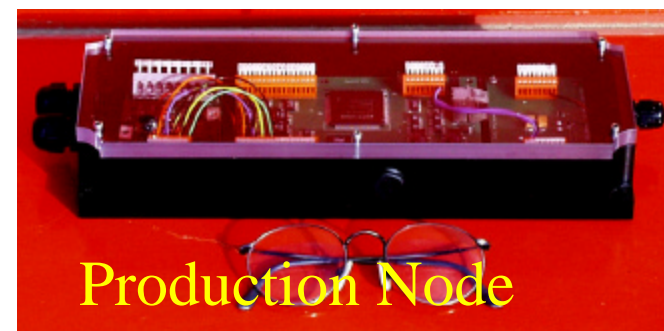
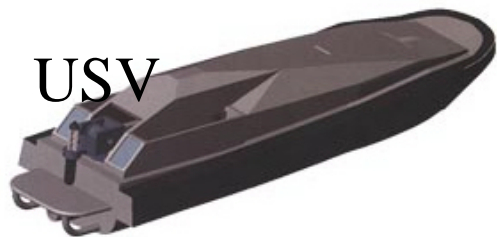
- Complete drive by wire multiplexed vessel
- Full redundancy (dual sensors, dual CAN, dual micro strategy)
- Safety critical systems dictate that control of bus must be maintained
- Significant strategy development to yield fail-safe systems design
- Open architecture must be achieved through managed gateways



seaborne targets



- HSMST
- QST-35
- QST-35 PI
- SDST
- Self Defense Test Ship
- Spartan USV Demonstration
- Other seaborne unmanned vehicles





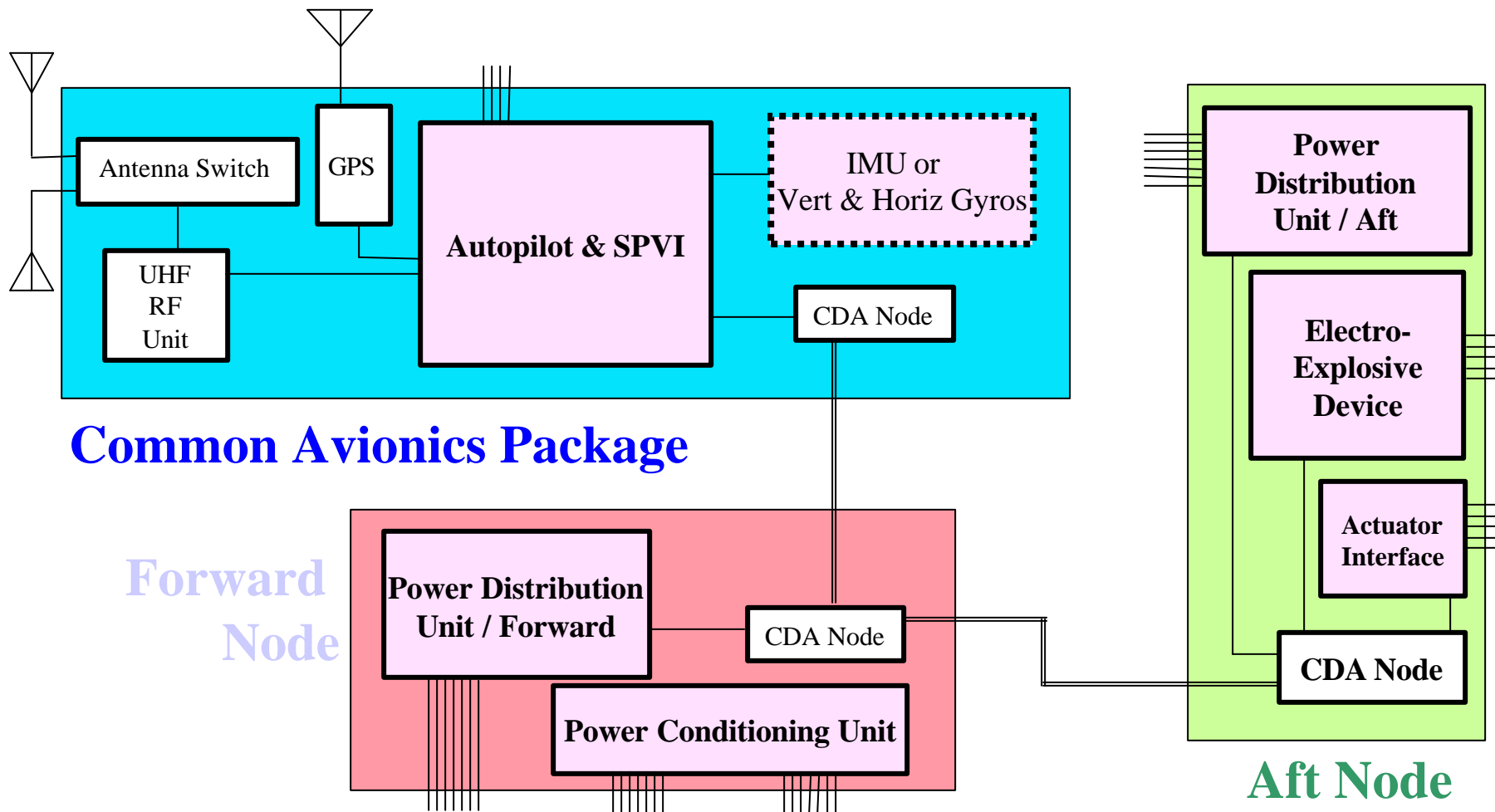
VTUAV



- Northrop-Grumman is using CDA technology in the VTUAV



MQM-107 CAP



Common Avionics Package

Forward Node

Aft Node

□ : Current Development □ : New Development



US army targets



MQM-107D/E



QUH-1



QAH-1

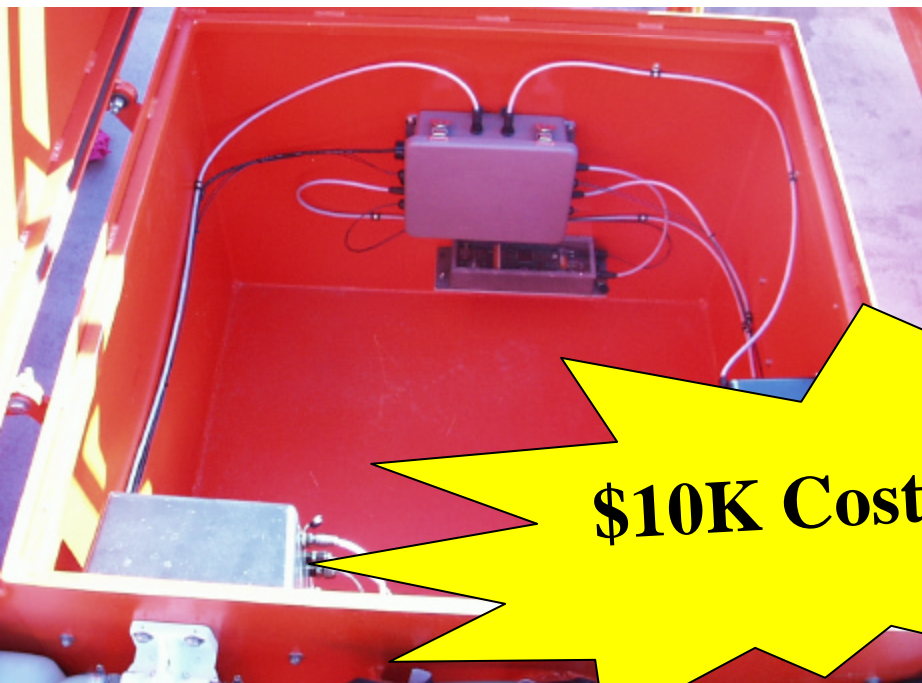


QH-50





any questions?



\$10K Cost Savings

**This is your
target with
CDA.**

**This is your
target without.**